

Removing the cocycle in a momentum map

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Abstract

We show that for a momentum map with a cocycle corresponding to a Hamiltonian G -action we can find a Hamiltonian action of a larger group whose momentum map extends the original one and is coadjoint equivariant.

The cocycle

Suppose we are given a Hamiltonian action ϕ of a connected Lie group G on the symplectic manifold (P, ω) with momentum mapping j , that is, for each vector ξ in the Lie algebra \mathfrak{g} of G , the infinitesimal generator Y_ξ of the action of G on P satisfies $Y_\xi \lrcorner \omega = dj_\xi$. The Poisson brackets of the components of j satisfy

$$\{j_\xi, j_\eta\} = j_{[\xi, \eta]} + \Sigma(\xi, \eta).$$

The momentum map j is equivariant with respect to an affine algebra action [7, p.42] of \mathfrak{g} on \mathfrak{g}^* . Σ is a two-cocycle because it is antisymmetric, bilinear and satisfies the cocycle identity

$$\Sigma([\xi, \eta], \zeta) + \Sigma([\eta, \zeta], \xi) + \Sigma([\zeta, \xi], \eta) = 0.$$

We are using the sign conventions of [1] and [2].

The extension

We try to make a new Lie algebra by first choosing a basis $\{X_a\}_{a=1}^n$ for \mathfrak{g} . The structure constants c_{ab}^c for \mathfrak{g} are defined by

$$[X_a, X_b] = c_{ab}^c X_c.$$

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Now add a new element Z and define the bracket relations for our new Lie algebra $\hat{\mathfrak{g}} = \mathfrak{g} \times_{\Sigma} \mathbb{R}$ by

$$\begin{aligned} [X_a, X_b] &= c_{ab}^c X_c + \Sigma_{ab} Z, \\ [X_a, Z] &= 0. \end{aligned}$$

We need to show that these bracket relations indeed define a Lie algebra. Since antisymmetry and bilinearity are clear, we need to check that the Jacobi identity holds. This follows because the cyclic sum

$$\mathfrak{S}[[X_a, X_b], X_c] = \mathfrak{S}(c_{ab}^e c_{ec}^d X_d + c_{ab}^e \Sigma_{ec}) = 0$$

by virtue of the Jacobi identity in \mathfrak{g} and the cocycle identity for Σ . The other possible brackets involve either one or two copies of Z , and these are easily seen to be zero since $[Z, *] = 0$. Hence we conclude that the bracket relations define a one-dimensional central extension of \mathfrak{g} . Note that $\mathfrak{z} = \mathbb{R}Z$ is an ideal in $\hat{\mathfrak{g}}$ and that $\hat{\mathfrak{g}}/\mathfrak{z} = \mathfrak{g}$.

Coadjoint equivariance

In order to show that the extended momentum map $\hat{j} = (j_1, \dots, j_n, j_Z)$ is coadjoint equivariant, first choose the basis (χ^a, ζ) for $\hat{\mathfrak{g}}^*$ dual to the basis (X_a, Z) for $\hat{\mathfrak{g}}$. The coadjoint action of $\hat{\mathfrak{g}}$ on $\hat{\mathfrak{g}}^*$ is given by

$$\begin{aligned} \text{ad}_{X_b}^t \zeta &= \Sigma_{bc} \chi^c, \\ \text{ad}_{X_b}^t \chi^a &= c_{bc}^a \chi^c, \\ \text{ad}_Z^t * &= 0. \end{aligned}$$

Let the extended connected, simply connected group \widehat{G} with Lie algebra $\hat{\mathfrak{g}}$ act on P by $\hat{\phi}(\hat{g}, p) = \phi(\rho(\hat{g}), p)$ where $\rho : \widehat{G} \rightarrow G$ is the quotient map. Infinitesimal equivariance may be seen from the following calculation:

$$\begin{aligned} \frac{d}{dt} \hat{j}(\hat{\phi}(\exp t X_b, p))|_{t=0} &= \langle d\hat{j}, Y_b \rangle \\ &= \omega(Y_a, Y_b) \chi^a \\ &= \{j_a, j_b\} \chi^a \\ &= c_{ab}^c j_c \chi^a + \Sigma_{ab} j_Z \chi^a \\ &= -\text{ad}_{X_b}^t (j_c \chi^c + j_Z \zeta). \end{aligned}$$

We conclude that the extended momentum map \hat{j} is coadjoint equivariant with respect to the extended algebra $\hat{\mathfrak{g}}$. Since \widehat{G} is connected, this proves the coadjoint equivariance of \hat{j} with respect to \widehat{G} as well.

Examples

The first example is the simplest. Let $P = \mathbb{R}^2$, $\omega = dq \wedge dp$, and $G = \mathbb{R}^2$ acting by translation:

$$\phi((x, y), (q, p)) = (q + x, p + y).$$

Then the cocycle is $\Sigma\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}\right) = 1$. The extended group \widehat{G} is the Heisenberg group with multiplication

$$(x, y, z) \cdot (x', y', z') = (x + x', y + y', z + z' + xy' - yx')$$

(note the cocycle term $\Sigma\left(\begin{pmatrix} x \\ y \end{pmatrix}, \begin{pmatrix} x' \\ y' \end{pmatrix}\right)$). The most illuminating representation for this group is as a subgroup of $\text{Sp}(4, \mathbb{R})$, given by matrices of the form

$$\begin{pmatrix} 1 & x & y & z \\ & 1 & 0 & y \\ & & 1 & -x \\ & & & 1 \end{pmatrix}.$$

This example is also given in [4, p.272]. It is much harder to see the symplectic role of the extension there because the authors employ the usual Heisenberg representation

$$\begin{pmatrix} 1 & x & z \\ & 1 & y \\ & & 1 \end{pmatrix}.$$

The next example is the extension of the affine symplectic group of the symplectic vector space \mathbb{R}^{2n} (the semidirect product $\text{Sp}(2n, \mathbb{R}) \ltimes \mathbb{R}^{2n}$) acting by symplectic affine transformations on \mathbb{R}^{2n} . In this case, the extended group may be identified with the odd symplectic group $\text{Sp}(2n + 1, \mathbb{R})$ [3], namely the group of matrices of form

$$\begin{pmatrix} 1 & & & \\ v & A & & \\ z & (JA^{-1}v)^t & 1 & \end{pmatrix},$$

where $v \in \mathbb{R}^{2n}$, $A \in \text{Sp}(2n, \mathbb{R})$, $z \in \mathbb{R}$, and J is the almost complex multiplication

$$J = \begin{pmatrix} 0 & I \\ -I & 0 \end{pmatrix}.$$

Remarks

A proof of this extension theorem (sans examples!) may also be found in Wallach [6]. However, it seems that (for reasons that escape us) the index calculation given here is more direct and more transparent than his coordinate-free one. The primary rationale for the new proof is that it helps one understand the affine symplectic group example given above more easily.

We further note that a discussion related to ours occurs in Woodhouse [7, p.58]. Moreover, this result was surely known to experts such as Tuynman [5], but they do not appear to have written it down.

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